# Almost Optimal Inapproximability of Multidimensional Packing Problems 

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## Plan

1. Introduction
2. Results
3. Vector Bin Packing
4. Summary
5. Vector Scheduling
6. Vector Bin Covering

## Packing Problems

- Input: $n$ items with sizes $a_{1}, a_{2}, \ldots, a_{n} \in[0,1]$.
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- Bin Covering: Maximize the number of bins, each bin should get at least 1 load.


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- All of them have a Polynomial Time Approximation Scheme (PTAS): $(1+\epsilon)$-factor approximation algorithm running in time poly $\left(n, \frac{1}{\epsilon}\right)$.
- Asymptotic approximation for Bin Packing: We study the setting when the optimal value is large enough.


## Multidimensional Packing Problems

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- Multidimensional problems: each job is a vector in $[0,1]^{d}$-Vector Bin Packing, Vector Scheduling, Vector Bin Covering.
- Motivation:

1. Fundamental problems in theory, well studied in the approximation algorithms community.
2. Most of the scheduling problems in practice are multidimensional.

## Vector Bin Packing

## Vector Bin Packing

- Input: $n d$-dimensional vectors $v_{1}, v_{2}, \ldots, v_{n} \in[0,1]^{d}$.
- Assign the jobs to minimum number of machines such that in each machine, the sum is at most 1 in every coordinate.



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- $d=$ 2: No PTAS (Woeginger, IPL 1997; Ray, 2021)
- $O(d)$-factor approximation algorithm. (De La Vega, Lueker, Combinatorica 1981)
- When $d$ is part of the input, essentially tight : $\Omega\left(d^{1-\epsilon}\right)$ NP-hardness (Chekuri, Khanna, SICOMP 2004)


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- Best Hardness: No PTAS for $d=2$.
- Question: Is there a constant factor approximation for Vector Bin Packing when the dimension is fixed?


## Vector Scheduling

## Vector Scheduling

- Input is $v_{1}, v_{2}, \ldots, v_{n} \in[0,1]^{d}$ and number of machines $m$.
- Find $f:[n] \rightarrow[m]$. Load vector on a machine $j \in[m]: \sum_{i \in[n]: f(i)=j} v_{i}$.
- Objective: Minimize the maximum $\ell_{\infty}$ norm of the load vectors.



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- Input: $n d$-dimensional vectors $v_{1}, v_{2}, \ldots, v_{n} \in[0,1]^{d}$.
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- Hardness: APX-Hard when $d=2$. (Ray, 2021)


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Assuming $P \neq N P$, Vector Bin Packing has no polynomial time algorithm with approximation factor $\Omega\left(\frac{\log d}{\log \log d}\right)$.

## Our results

| Problem | Subcase | Best Algorithm | Best Hardness |
| :---: | :---: | :---: | :---: |
| VBP | $d=1$ | PTAS | NP-Hard |
|  | Fixed d | $\ln d+O(1)$ | $\Omega(\log d)$ |
|  | Arbitrary d | $1+\epsilon d+O\left(\ln \frac{1}{\epsilon}\right)$ | $d^{1-\epsilon}$ |
| VS | $d=1$ | PTAS | NP-Hard |
|  | Fixed d | PTAS | NP-Hard |
|  | Arbitrary d | $O\left(\frac{\log d}{\log \log d}\right)$ | $\begin{aligned} & \Omega\left((\log d)^{1-\epsilon}\right) \\ & \left(\operatorname{NP} \nsubseteq \operatorname{ZPTIME}\left(n^{(\log n)^{O(1)}}\right)\right) \end{aligned}$ |
| VBC | $d=1$ | FPTAS | NP-Hard |
|  | Arbitrary d | $O(\log d)$ | $\Omega\left(\frac{\log d}{\log \log d}\right)$ |

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- Recall the problem statement: Input is $v_{1}, v_{2}, \ldots, v_{n} \in[0,1]^{d}$. Objective: Partition them into minimum number of parts such that in each part, the sum of the vectors is at most 1 in every coordinate.


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- Configuration: A subset $\left\{i_{1}, i_{2}, \ldots, i_{k}\right\} \subseteq[n]$ is called a configuration if

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\left\|v_{i_{1}}+v_{i_{2}}+\ldots+v_{i_{k}}\right\|_{\infty} \leq 1
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- Objective is to use the minimum number of configurations to cover [ $n$ ].


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- Objective is to use the minimum number of configurations to cover [ $n$ ].
- Using the minimum number of sets from a given family to cover all the elements: Set Cover Problem.



## Reversing the Reduction



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Which Set Cover instances can be formulated as d-dimensional Vector Bin Packing instances?

- Given a set family $\mathcal{F} \subseteq 2^{[n]}$, goal is to find vectors $v_{1}, v_{2}, \ldots, v_{n} \in[0,1]^{d}$ such that for every set $S \subseteq[n], S \in \mathcal{F}$ if and only if

$$
\left\|\sum_{i \in S} v_{i}\right\|_{\infty} \leq 1
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## Packing Dimension

- Packing Dimension of $\mathcal{F} \subseteq 2^{[n]} \operatorname{pdim}(\mathcal{F})$ is the smallest positive integer $d$ such that there exist vectors $v_{1}, v_{2}, \ldots, v_{n} \in[0,1]^{d}$ with

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v_{2}=(0.4)
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- $\mathcal{F}$ is downward-closed i.e., if $S \in \mathcal{F}$, then $T \in \mathcal{F}$ for all $T \subseteq S$.
- No isolated elements: For every $i \in[n]$, there exists $S \in \mathcal{F}: i \in S$.
- These two conditions are sufficient.

$$
\mathcal{F}=\{\phi,\{1\},\{2\},\{3\},\{1,2\},\{2,3\}\}
$$

## Hardness of VBP

- Observation: If $\operatorname{pdim}(\mathcal{F}) \leq d$, the Set Cover problem on $\mathcal{F}$ is a $d$-dimensional Vector Bin Packing problem.


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Packing Dimension of $\mathcal{F}$ is at most $d$ Set Cover is Hard to approximate within $f(d)$ on $\mathcal{F}$

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\text { VBP is Hard to approximate within } f(d)
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## Choosing the Set Family

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- Set Cover: $\Omega(\ln n)$ hardness. (Feige, JACM 1998)
- Packing Dimension of these hard instances grows with $n \oplus$
- Question: Are there structured set families that have small Packing Dimension but the Set Cover problem is hard on them?
- Answer: Simple Bounded Set Families. ©


## Simple Bounded Set Families

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- $(k, \Delta)$-Bounded: Each set has cardinality at most $k$, and each element appears in at most $\Delta$ sets.


## Set Cover on Simple Bounded Set Families

Set Cover is hard to approximate within $\Omega(\ln k)$ factor on simple $(k, \Delta)$-bounded set families with $\Delta=k^{O(1)}$, when $k$ is a large constant.

- Proof: Essentially (Anil Kumar, Arya, Ramesh, ICALP 2000), start with a modified Label Cover instance.


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## Packing Dimension of Simple Bounded Set Families

Suppose that $\mathcal{F}$ is a simple $(k, \Delta)$-bounded set family with no isolated elements. Then,

$$
\operatorname{pdim}\left(\mathcal{F}^{\downarrow}\right) \leq(k \Delta)^{O(1)}
$$

## A property of Packing Dimension

```
Sub-additivity of Packing Dimension
pdim}(\mp@subsup{\mathcal{F}}{1}{}\cap\mp@subsup{\mathcal{F}}{2}{})\mathrm{ is at most }\operatorname{pdim}(\mp@subsup{\mathcal{F}}{1}{})+\operatorname{pdim}(\mp@subsup{\mathcal{F}}{2}{})
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## A property of Packing Dimension

## Sub-additivity of Packing Dimension <br> $\operatorname{pdim}\left(\mathcal{F}_{1} \cap \mathcal{F}_{2}\right)$ is at most $\operatorname{pdim}\left(\mathcal{F}_{1}\right)+\operatorname{pdim}\left(\mathcal{F}_{2}\right)$.

- Proof: $f_{1}:[n] \rightarrow[0,1]^{d_{1}}$ such that for every $S \subseteq[n], S \in \mathcal{F}_{1}$ if and only if

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\left\|\sum_{i \in S} f_{1}(i)\right\|_{\infty} \leq 1
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Similarly, $f_{2}:[n] \rightarrow[0,1]^{d_{2}}$.

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- Define $f:[n] \rightarrow[0,1]^{d_{1}+d_{2}}$ as $\left(f_{1}(i), f_{2}(i)\right)$. For every $S \subseteq[n]$,

$$
\left\|\sum_{i \in S} f(i)\right\|_{\infty} \leq 1
$$

if and only if $S \in \mathcal{F}_{1}$ and $S \in \mathcal{F}_{2}$.

## Sunflower Bouquets

- Writing a simple bounded set family as an intersection of small number of structured set families with small Packing Dimension?


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- Writing a simple bounded set family as an intersection of small number of structured set families with small Packing Dimension?
- Yes, using Sunflower-Bouquets.


## ( $k, \Delta$ )-Sunflower Bouquet with core $U$

1. Every set $S \in \mathcal{F}$ intersects with $U$ exactly once.
2. Intersection of any two sets is either empty or is in $U$.
3. Each set has cardinality at most $k$, each element appears in at most $\Delta$ sets.


## Embedding of Sunflower Bouquets

## Embedding of Sunflower Bouquets (Main Technical Lemma)

Suppose that $\mathcal{F} \subseteq 2^{[n]}$ is a $(k, \Delta)$-Sunflower with core $U$. Then, there exists an embedding $f:[n] \rightarrow[0,1]^{d}$ with $d=\operatorname{poly}(k, \Delta)$ such that

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1. For every set $S \in \mathcal{F},\left\|\sum_{i \in S} f(i)\right\|_{\infty} \leq 1$.
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3. For every set $S$ with $S \cap U \neq \phi$ and $|S| \leq k,\left\|\sum_{i \in S} f(i)\right\|_{\infty} \leq 1$.

- High level idea: many embeddings, each satisfying 1 . and 3.

1. Eliminating "inter-sunflower" sets.
2. Pinning the "intra-sunflower" sets.

## Inter-Sunflower sets



## Inter-Sunflower sets



## Intra-Sunflower sets

- For every minimal set $S \notin \mathcal{F}^{\downarrow}$ with $S \cap U \neq \phi$, we create a coordinate such that the sum is greater than 1.
- There are only $O\left((k \Delta)^{2}\right)$ such minimal sets in a sunflower.


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- $\mathcal{F} \subseteq 2^{[n]}$ : Simple $(k, \Delta)$-Bounded set family.
- Color [ $n$ ] with $L$ colors such that

1. All the elements in an edge are assigned distinct colors.
2. If two edges intersect, all their elements are assigned distinct colors.

- Note: $L=O\left((k \Delta)^{2}\right)$ suffices.


## Packing Dimension of Simple Bounded Set Families

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- Note: $L=O\left((k \Delta)^{2}\right)$ suffices.
- $\mathcal{F}_{i} \subseteq \mathcal{F}$ : all the sets that hit the ith color. $\mathcal{F}_{i}$ is a Sunflower-Bouquet!



## Packing Dimension of Simple Bounded Set Families

- Use the Embedding of Sunflower-Bouquets for every $\mathcal{F}_{i}, f_{i}:[n] \rightarrow[0,1]^{d}$ with $d=\operatorname{poly}(k, \Delta)$ such that

1. For every set $S \in \mathcal{F}_{i},\left\|\sum_{i \in S} f(i)\right\|_{\infty} \leq 1$.
2. For every set $S \notin \mathcal{F}_{i}^{\downarrow}$ with $S \cap U_{i} \neq \phi,\left\|\sum_{i \in S} f(i)\right\|_{\infty}>1$.
3. For every set $S$ with $S \cap U_{i} \neq \phi$ and $|S| \leq k,\left\|\sum_{i \in S} f(i)\right\|_{\infty} \leq 1$.

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- Use the Embedding of Sunflower-Bouquets for every $\mathcal{F}_{i}, f_{i}:[n] \rightarrow[0,1]^{d}$ with $d=\operatorname{poly}(k, \Delta)$ such that

1. For every set $S \in \mathcal{F}_{i},\left\|\sum_{i \in S} f(i)\right\|_{\infty} \leq 1$.
2. For every set $S \notin \mathcal{F}_{i}^{\downarrow}$ with $S \cap U_{i} \neq \phi,\left\|\sum_{i \in S} f(i)\right\|_{\infty}>1$.
3. For every set $S$ with $S \cap U_{i} \neq \phi$ and $|S| \leq k,\left\|\sum_{i \in S} f(i)\right\|_{\infty} \leq 1$.

- Final embedding $f=\left(f_{1}, f_{2}, \ldots, f_{L}\right)$

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- Completes the proof that $\operatorname{pdim}(\mathcal{F})$ is at most $\operatorname{poly}(k, \Delta)$.


## Hardness of Vector Bin Packing

- The Packing Dimension of Simple $(k, \Delta)$-Bounded set families is at most poly $(k, \Delta)$.
- Set Cover on Simple $(k, \Delta)$-Bounded set families is hard to approximate within $\Omega(\log k)$ when $\Delta=k^{O(1)}$ and $k$ is a large constant.


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- Both together prove that $d$-dimensional Vector Bin Packing is hard to approximate within $\Omega(\log d)$ factor when $d$ is a large constant.


## Plan

## 1. Introduction

## 2. Results

3. Vector Bin Packing
4. Summary
5. Vector Scheduling
6. Vector Bin Covering

## Summary

- Hardness of Multidimensional Packing Problems: Vector Bin Packing, Vector Scheduling, Vector Bin Covering.
- Vector Bin Packing: Packing Dimension.
- Open Problems: Other applications of Packing Dimension? Hardness of Geometric Bin Packing? Better hardness for 2-dimensional Bin Packing?



## Plan

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## Our results

## Vector Bin Packing Assuming $P \neq N P$, when $d$ is fixed, Vector Bin Packing is hard to approximate within $\Omega(\log d)$ factor

## Vector Scheduling

Assuming NP has no quasipolynomial time algorithms, Vector Scheduling has no $\Omega\left((\log d)^{1-\epsilon}\right)$ factor polynomial time algorithms for all $\epsilon>0$.

## Assuming $P \neq N P$, Vector Bin Packing has no polynomial time algorithm with approximation

 factor $\Omega\left(\frac{\log d}{\log \log d}\right)$
## Vector Scheduling

- Input: $v_{1}, v_{2}, \ldots, v_{n} \in[0,1]^{d}$, and $m$, the number of machines.
- Find $f:[n] \rightarrow[m]$. Load vector on a machine $j \in[m]: \sum_{i \in[n]: f(i)=j} v_{i}$.
- Objective: Minimize the maximum $\ell_{\infty}$ norm of the load vectors.


## Monochromatic Clique

- Monochromatic Clique $(k, B)$ : Given a graph $G=([n], E)$, and parameters $k:=k(n), B:=B(n)$, the goal is to distinguish between

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- $B=2$ : Standard $k$-coloring of graphs.
- Problem gets easier as $B$ increases.
- When $B=\sqrt{n}$, the problem can be solved in polynomial time.


## Hardness of Vector Scheduling from Monochromatic Clique

- Suppose that Monochromatic $\operatorname{Clique}(k, B)$ is hard.


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- Define $\mathcal{V}=\left\{v_{1}, v_{2}, \ldots, v_{n}\right\} \subseteq\{0,1\}^{d}$ as

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\left(v_{i}\right)_{j}= \begin{cases}1 & \text { if } i \in T_{j} \\ 0 & \text { otherwise }\end{cases}
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The number of machines is equal to $k$.

- Completeness: If $G$ is $k$-colorable, there is an assignment with maximum $\ell_{\infty}$ value 1 .
- Soundness: If in any assignment of $k$-colors to the vertices of $G$ there exists a clique of size $B$, the load is at least $B$ in any scheduling.


## Hardness of Monochromatic Clique

- For every constant $B$, there exists $k:=k(n)$ such that Monochromatic Clique $(k, B)$ is NP-Hard. (Chekuri, Khanna, SICOMP 2004)


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- Question: Can we prove improved hardness of Monochromatic Clique $(k, B)$ when $B$ is larger?
- Answer: Yes, using Lexicographic graph product based amplification.


## Hardness of Vector Scheduling

Graph Coloring Hardness of Approximation (Khot, FOCS 2001)


## Strong Monochromatic Clique

- Strong Monochromatic Clique $(k, B, C)$ : A generalization of Monochromatic Clique: Given a graph $G=([n], E)$, parameters $k:=k(n), B:=B(n), C$, the goal is to distinguish between

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## Hardness of Strong Monochromatic Clique

Assuming NP has no quasipolynomial time algorithm, there exist constant $\gamma>0$ and $k:=k(n)$ such that Strong Monochromatic Clique $\left(k,(\log n)^{\gamma}, C\right)$ has no quasipolynomial time algorithm for all integers $C \geq 1$.

## Lexicographic Product

- $G=G_{1} \times G_{2}$. Vertex set of $G$ is $V_{1} \times V_{2}$.
- Two vertices $\left(u_{1}, u_{2}\right)$ and $\left(v_{1}, v_{2}\right)$ are adjacent in $G$ if
- $\left(u_{1}, v_{1}\right)$ are adjacent in $G_{1}$, or
- $u_{1}=v_{1}$, and ( $u_{2}, v_{2}$ ) are adjacent in $G_{2}$


[^0]
## Hardness Amplication using Lexicographic Product

- Reduction from Strong Monochromatic Clique $(k, B, C)$ to Monochromatic Clique $\left(k^{C}, B^{C}\right)$.


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- Reduction from Strong Monochromatic Clique $(k, B, C)$ to Monochromatic Clique $\left(k^{C}, B^{C}\right)$.
- Let $G^{2}=G \times G$.
- Completeness: If $\chi(G) \leq k$, then $\chi\left(G^{2}\right) \leq k^{2}$. If $c: V(G) \rightarrow[k]$ is a proper $k$-coloring of $G$, simply assign $\left(c\left(u_{1}\right), c\left(u_{2}\right)\right)$ to $\left(u_{1}, u_{2}\right)$.


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- Soundness: Suppose that in any assignment of $k^{2}$ colors to $V(G)$, there is a monochromatic clique of size $B$.
- Consider an assignment $c: V\left(G^{2}\right) \rightarrow\left[k^{2}\right]$.
- For every $u \in V(G)$, there is a clique of size $B\left(u, v_{1}\right),\left(u, v_{2}\right), \ldots,\left(u, v_{B}\right)$ in $G^{2}$ that are all assigned the same color $c^{\prime}(u)$.


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- $c^{\prime}$ itself is a coloring of $V(G)$, there is a clique of size $B, u_{1}, u_{2}, \ldots, u_{B}$ that have the same $c^{\prime}$ value.


## Hardness Amplification Using Lexicographic Product

- Let $G^{\prime}=G^{C}$.

1. Completeness: If $\chi(G) \leq k$, then $\chi\left(G^{\prime}\right) \leq k^{C}$.
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- Polynomial time reduction from Strong Monochromatic Clique ( $k, B, C$ ) to Monochromatic Clique ( $k^{C}, B^{C}$ ).


## Hardness of Monochromatic Clique

Assuming NP has no quasipolynomial time algorithm, for every $C$, there exists $k:=k(n)$ such that Monochromatic Clique $\left(k,(\log n)^{C}\right)$ has no quasipolynomial time algorithm.

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## Hardness of Vector Scheduling

Assuming NP has no quasipolynomial time algorithm, Vector Scheduling has no polynomial time algorithm with approximation ratio $\Omega\left((\log d)^{1-\epsilon}\right)$ for all $\epsilon>0$.

## Our results

```
Vector Bin Packing
factor
```

Vector Scheduling
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$\Omega\left((\log d)^{1-\epsilon}\right)$ factor polynomial time algorithms for all $\epsilon>0$.

## Vector Bin Covering

Assuming $P \neq N P$, Vector Bin Packing has no polynomial time algorithm with approximation factor $\Omega\left(\frac{\log d}{\log \log d}\right)$.

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## Vector Bin Covering

- Input: $n$ vectors $v_{1}, v_{2}, \ldots, v_{n} \in[0,1]^{d}$. Objective: Partition them into the maximum number of parts such that in each part, the sum is at least 1 in every coordinate.


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- View each vector as a vertex of a hypergraph and each coordinate as an edge of the hypergraph.
- Given a hypergraph, objective is to partition the vertex set into maximum number of parts such that every part hits each edge.
- Such a coloring of hypergraphs: Rainbow Coloring.


## Hypergraph Rainbow Coloring

- Hypergraph $H=(V, E)$, find $c: V \rightarrow[k]$ such that

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\bigcup_{v \in e} c(v)=[k] \quad \forall e \in E
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- When $k=2$, same as 2 -coloring of hypergraphs. NP-Hard.


## Approximate Rainbow Coloring Hardness

Given a hypergraph $H$ with $m$ edges, it is NP-Hard to distinguish between

1. $H$ is 2-colorable.
2. $H$ cannot be rainbow colored with $\Omega\left(\frac{\log m}{\log \log m}\right)$ colors.

## Hardness of approximate Rainbow Coloring



## Label Cover

In the Label Cover problem, the input is a bipartite graph $U \cup V, E$ with projection constraints $\Pi_{e}: \Sigma \rightarrow \Sigma$ on each edge.

- The objective is to assign labels from $\Sigma$ to the vertices to satisfy as many constraints as possible.
- Very hard to approximate: NP-Hard to find a labeling satisfying $\epsilon$ fraction of the constraints on fully satisfiable instances.
- "Mother of most optimal inapproximability results".


## Approximate Rainbow Coloring Hardness

- Gadget reduction based on Label Cover-Long Code framework.


## Approximate Rainbow Coloring Hardness

- Gadget reduction based on Label Cover-Long Code framework.
- Difference from the previous results: we now use very weak Label Cover hardness.
- We just use NP-Hardness of Label Cover, so alphabet size is $O(1)$.


[^0]:    Image Credit: Wikipedia, Author=David Eppstein

