Almost Optimal Inapproximability of Multidimensional Packing Problems

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1. Introduction

- 2. Results
- 3. Vector Bin Packing
- 4. Summary
- 5. Vector Scheduling
- 6. Vector Bin Covering

- Input: *n* items with sizes $a_1, a_2, \ldots, a_n \in [0, 1]$.
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- Asymptotic approximation for Bin Packing: We study the setting when the optimal value is large enough.

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- Motivation:
 - 1. Fundamental problems in theory, well studied in the approximation algorithms community.
 - 2. Most of the scheduling problems in practice are multidimensional.

Vector Bin Packing

Vector Bin Packing

- Input: *n d*-dimensional vectors $v_1, v_2, \ldots, v_n \in [0, 1]^d$.
- Assign the jobs to minimum number of machines such that in each machine, the sum is at most 1 in every coordinate.



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- *d* = 2: No PTAS (Woeginger, IPL 1997; Ray, 2021)
- O(d)-factor approximation algorithm. (De La Vega, Lueker, Combinatorica 1981)
- When d is part of the input, essentially tight : $\Omega(d^{1-\epsilon})$ NP-hardness (Chekuri, Khanna, SICOMP 2004)

• When d is fixed, the algorithms can now run in $n^{f(d)}$ time, for some function f.

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- Best Hardness: No PTAS for d = 2.
- Question: Is there a constant factor approximation for Vector Bin Packing when the dimension is fixed?

Vector Scheduling

Vector Scheduling

- Input is $v_1, v_2, \ldots, v_n \in [0, 1]^d$ and number of machines m.
- Find $f:[n] \to [m]$. Load vector on a machine $j \in [m]: \sum_{i \in [n]: f(i)=j} v_i$.
- Objective: Minimize the maximum ℓ_∞ norm of the load vectors.



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- Hardness: No constant factor approximation algorithm. (Chekuri, Khanna, SICOMP 2004)

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- Hardness: APX-Hard when d = 2. (Ray, 2021)



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Assuming $P \neq NP$, when d is fixed, Vector Bin Packing is hard to approximate within $\Omega(\log d)$ factor.

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Assuming $P \neq NP$, Vector Bin Packing has no polynomial time algorithm with approximation factor $\Omega\left(\frac{\log d}{\log \log d}\right)$.

Problem	Subcase	Best Algorithm	Best Hardness
VBP	d = 1 Fixed d Arbitrary d	$\begin{array}{c} PTAS \\ \ln d + O(1) \\ 1 + \epsilon d + O\left(\ln \frac{1}{\epsilon}\right) \end{array}$	${f NP} ext{-Hard}\ {f \Omega}(\log d)\ d^{1-\epsilon}$
VS	d = 1 Fixed d Arbitrary d	$\begin{array}{c} PTAS \\ PTAS \end{array}$ $O\left(\frac{\log d}{\log\log d}\right)$	$\begin{array}{l} NP\text{-Hard} \\ NP\text{-Hard} \\ \Omega\left((\log d)^{1-\epsilon}\right) \\ \left(NP \notin ZPTIME\left(n^{(\log n)^{O(1)}}\right)\right) \end{array}$
VBC	d = 1 Arbitrary d	$\begin{array}{c} FPTAS \\ O(\log d) \end{array}$	$\begin{array}{c} NP\text{-Hard} \\ \Omega\left(\frac{\log d}{\log\log d}\right) \end{array}$



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Recall the problem statement: Input is v₁, v₂,..., v_n ∈ [0,1]^d. Objective: Partition them into minimum number of parts such that in each part, the sum of the vectors is at most 1 in every coordinate.

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- Recall the problem statement: Input is v₁, v₂,..., v_n ∈ [0,1]^d. Objective: Partition them into minimum number of parts such that in each part, the sum of the vectors is at most 1 in every coordinate.
- Configuration: A subset $\{i_1, i_2, \dots, i_k\} \subseteq [n]$ is called a configuration if

$$\|v_{i_1} + v_{i_2} + \ldots + v_{i_k}\|_{\infty} \leq 1$$

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- Objective is to use the minimum number of configurations to cover [n].
- Using the minimum number of sets from a given family to cover all the elements: Set Cover Problem.



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Which Set Cover instances can be formulated as *d*-dimensional Vector Bin Packing instances?

• Given a set family $\mathcal{F} \subseteq 2^{[n]}$, goal is to find vectors $v_1, v_2, \ldots, v_n \in [0, 1]^d$ such that for every set $S \subseteq [n]$, $S \in \mathcal{F}$ if and only if

$$\left\|\sum_{i\in S} v_i\right\|_{\infty} \leq 1$$

Packing Dimension of *F* ⊆ 2^[n] pdim(*F*) is the smallest positive integer *d* such that there exist vectors v₁, v₂,..., v_n ∈ [0, 1]^d with

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 - No isolated elements: For every *i* ∈ [*n*], there exists *S* ∈ *F* : *i* ∈ *S*.
- These two conditions are sufficient.



$$\mathcal{F} = \{\phi, \{1\}, \{2\}, \{3\}, \{1,2\}, \{2,3\}\}$$

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- Question: Are there structured set families that have small Packing Dimension but the Set Cover problem is hard on them?
- Answer: Simple Bounded Set Families. ©

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Set Cover on Simple Bounded Set Families

Set Cover is hard to approximate within $\Omega(\ln k)$ factor on simple (k, Δ) -bounded set families with $\Delta = k^{O(1)}$, when k is a large constant.

• Proof: Essentially (Anil Kumar, Arya, Ramesh, ICALP 2000), start with a modified Label Cover instance.

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Packing Dimension of Simple Bounded Set Families

Suppose that \mathcal{F} is a simple (k, Δ) -bounded set family with no isolated elements. Then,

 $\mathsf{pdim}(\mathcal{F}^{\downarrow}) \leq (k\Delta)^{O(1)}$

A property of Packing Dimension

Sub-additivity of Packing Dimension

 $\mathsf{pdim}(\mathcal{F}_1 \cap \mathcal{F}_2)$ is at most $\mathsf{pdim}(\mathcal{F}_1) + \mathsf{pdim}(\mathcal{F}_2)$.

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• Proof: $f_1: [n] \rightarrow [0,1]^{d_1}$ such that for every $S \subseteq [n]$, $S \in \mathcal{F}_1$ if and only if

$$\left\|\sum_{i\in S} f_1(i)\right\|_{\infty} \leq 1$$

Similarly, $f_2 : [n] \to [0, 1]^{d_2}$.

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• Define $f:[n] \rightarrow [0,1]^{d_1+d_2}$ as $(f_1(i), f_2(i))$. For every $S \subseteq [n]$,

$$\left\|\sum_{i\in\mathcal{S}}f(i)\right\|_{\infty}\leq 1$$

if and only if $S \in \mathcal{F}_1$ and $S \in \mathcal{F}_2$.

Sunflower Bouquets

• Writing a simple bounded set family as an intersection of small number of structured set families with small Packing Dimension?

Sunflower Bouquets

- Writing a simple bounded set family as an intersection of small number of structured set families with small Packing Dimension?
- Yes, using Sunflower-Bouquets.

(k,Δ) -Sunflower Bouquet with core U

- 1. Every set $S \in \mathcal{F}$ intersects with U exactly once.
- 2. Intersection of any two sets is either empty or is in U.
- 3. Each set has cardinality at most k, each element appears in at most Δ sets.



Suppose that $\mathcal{F} \subseteq 2^{[n]}$ is a (k, Δ) -Sunflower with core U. Then, there exists an embedding $f : [n] \to [0, 1]^d$ with $d = \text{poly}(k, \Delta)$ such that

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- 1. For every set $S \in \mathcal{F}$, $\|\sum_{i \in S} f(i)\|_{\infty} \leq 1$.
- 2. For every set $S \notin \mathcal{F}^{\downarrow}$ with $S \cap U \neq \phi$, $\|\sum_{i \in S} f(i)\|_{\infty} > 1$.

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3. For every set S with $S \cap U \neq \phi$ and $|S| \leq k$, $\|\sum_{i \in S} f(i)\|_{\infty} \leq 1$.

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3. For every set S with $S \cap U \neq \phi$ and $|S| \leq k$, $\|\sum_{i \in S} f(i)\|_{\infty} \leq 1$.

- High level idea: many embeddings, each satisfying 1. and 3.
 - 1. Eliminating "inter-sunflower" sets.
 - 2. Pinning the "intra-sunflower" sets.

Inter-Sunflower sets



Inter-Sunflower sets



Intra-Sunflower sets



- For every minimal set S ∉ F[↓] with S ∩ U ≠ φ, we create a coordinate such that the sum is greater than 1.
- There are only $O((k\Delta)^2)$ such minimal sets in a sunflower.

Packing Dimension of Simple Bounded Set Families

• $\mathcal{F} \subseteq 2^{[n]}$: Simple (k, Δ) -Bounded set family.
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- Color [n] with L colors such that
 - 1. All the elements in an edge are assigned distinct colors.
 - 2. If two edges intersect, all their elements are assigned distinct colors.
- Note: $L = O((k\Delta)^2)$ suffices.

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- Note: $L = O((k\Delta)^2)$ suffices.
- $\mathcal{F}_i \subseteq \mathcal{F}$: all the sets that hit the *i*th color. \mathcal{F}_i is a Sunflower-Bouquet!



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- Use the Embedding of Sunflower-Bouquets for every \mathcal{F}_i , $f_i : [n] \to [0,1]^d$ with $d = \text{poly}(k, \Delta)$ such that
 - 1. For every set $S \in \mathcal{F}_i$, $\|\sum_{i \in S} f(i)\|_{\infty} \leq 1$.
 - 2. For every set $S \notin \mathcal{F}_i^{\downarrow}$ with $S \cap U_i \neq \phi$, $\|\sum_{i \in S} f(i)\|_{\infty} > 1$.
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 - 3. For every set S with $S \cap U_i \neq \phi$ and $|S| \leq k$, $\|\sum_{i \in S} f(i)\|_{\infty} \leq 1$.
- Final embedding $f = (f_1, f_2, \dots, f_L)$
 - 1. For every set $S \in \mathcal{F}$, $\|\sum_{i \in S} f(i)\|_{\infty} \leq 1$.
 - 2. For every set $S \notin \mathcal{F}^{\downarrow}$, $\|\sum_{i \in S} f(i)\|_{\infty} > 1$.
- Completes the proof that pdim(*F*) is at most poly(k, Δ).

- The Packing Dimension of Simple (k, Δ) -Bounded set families is at most $poly(k, \Delta)$.
- Set Cover on Simple (k, Δ) -Bounded set families is hard to approximate within $\Omega(\log k)$ when $\Delta = k^{O(1)}$ and k is a large constant.

- The Packing Dimension of Simple (k, Δ) -Bounded set families is at most $poly(k, \Delta)$.
- Set Cover on Simple (k, Δ) -Bounded set families is hard to approximate within $\Omega(\log k)$ when $\Delta = k^{O(1)}$ and k is a large constant.
- Both together prove that *d*-dimensional Vector Bin Packing is hard to approximate within $\Omega(\log d)$ factor when *d* is a large constant.



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- Hardness of Multidimensional Packing Problems: Vector Bin Packing, Vector Scheduling, Vector Bin Covering.
- Vector Bin Packing: Packing Dimension.
- Open Problems: Other applications of Packing Dimension? Hardness of Geometric Bin Packing? Better hardness for 2-dimensional Bin Packing?



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Vector Scheduling

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Vector Bin Covering

Assuming $P \neq NP$, Vector Bin Packing has no polynomial time algorithm with approximation factor $\Omega\left(\frac{\log d}{\log \log d}\right)$.

- Input: $v_1, v_2, \ldots, v_n \in [0, 1]^d$, and *m*, the number of machines.
- Find $f:[n] \to [m]$. Load vector on a machine $j \in [m]: \sum_{i \in [n]: f(i)=j} v_i$.
- Objective: Minimize the maximum ℓ_∞ norm of the load vectors.

- Monochromatic Clique(k, B): Given a graph G = ([n], E), and parameters k := k(n), B := B(n), the goal is to distinguish between
 - 1. *G* is *k*-colorable.
 - 2. In any assignment of k-colors to the vertices of G, there is a monochromatic clique of size B.

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 - 1. *G* is *k*-colorable.
 - 2. In any assignment of k-colors to the vertices of G, there is a monochromatic clique of size B.
- *B* = 2: Standard *k*-coloring of graphs.

- Monochromatic Clique(k, B): Given a graph G = ([n], E), and parameters k := k(n), B := B(n), the goal is to distinguish between
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- Problem gets easier as B increases.
- When $B = \sqrt{n}$, the problem can be solved in polynomial time.

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- Completeness: If G is k-colorable, there is an assignment with maximum ℓ_{∞} value 1.
- Soundness: If in any assignment of *k*-colors to the vertices of *G* there exists a clique of size *B*, the load is at least *B* in any scheduling.

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- Question: Can we prove improved hardness of Monochromatic Clique (k, B) when B is larger?
- Answer: Yes, using Lexicographic graph product based amplification.

Hardness of Vector Scheduling



Strong Monochromatic Clique

- Strong Monochromatic Clique(k, B, C): A generalization of Monochromatic Clique: Given a graph G = ([n], E), parameters k := k(n), B := B(n), C, the goal is to distinguish between
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Hardness of Strong Monochromatic Clique

Assuming NP has no quasipolynomial time algorithm, there exist constant $\gamma > 0$ and k := k(n) such that Strong Monochromatic Clique $(k, (\log n)^{\gamma}, C)$ has no quasipolynomial time algorithm for all integers $C \ge 1$.

Lexicographic Product

- $G = G_1 \times G_2$. Vertex set of G is $V_1 \times V_2$.
- Two vertices (u_1, u_2) and (v_1, v_2) are adjacent in G if
 - (u_1, v_1) are adjacent in G_1 , or
 - $u_1 = v_1$, and (u_2, v_2) are adjacent in G_2



Image Credit: Wikipedia, Author=David Eppstein

Reduction from Strong Monochromatic Clique (k, B, C) to Monochromatic Clique (k^C, B^C).

- Reduction from Strong Monochromatic Clique (k, B, C) to Monochromatic Clique (k^{C}, B^{C}) .
- Let $G^2 = G \times G$.
- Completeness: If χ(G) ≤ k, then χ(G²) ≤ k². If c : V(G) → [k] is a proper k-coloring of G, simply assign (c(u₁), c(u₂)) to (u₁, u₂).

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 - c' itself is a coloring of V(G), there is a clique of size B, u_1, u_2, \ldots, u_B that have the same c' value.

- Let $G' = G^C$.
 - 1. Completeness: If $\chi(G) \leq k$, then $\chi(G') \leq k^{C}$.
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Hardness of Vector Scheduling

Assuming NP has no quasipolynomial time algorithm, Vector Scheduling has no polynomial time algorithm with approximation ratio $\Omega((\log d)^{1-\epsilon})$ for all $\epsilon > 0$.

Our results

Vector Bin Packing

Assuming $P \neq NP$, when d is fixed, Vector Bin Packing is hard to approximate within $\Omega(\log d)$ factor.

Vector Scheduling

Assuming NP has no quasipolynomial time algorithms, Vector Scheduling has no $\Omega((\log d)^{1-\epsilon})$ factor polynomial time algorithms for all $\epsilon > 0$.

Vector Bin Covering

Assuming $P \neq NP$, Vector Bin Packing has no polynomial time algorithm with approximation factor $\Omega\left(\frac{\log d}{\log \log d}\right)$.

1. Introduction

- 2. Results
- 3. Vector Bin Packing
- 4. Summary
- 5. Vector Scheduling
- 6. Vector Bin Covering
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- Given a hypergraph, objective is to partition the vertex set into maximum number of parts such that every part hits each edge.
- Such a coloring of hypergraphs: Rainbow Coloring.

Hypergraph Rainbow Coloring

• Hypergraph H = (V, E), find $c : V \rightarrow [k]$ such that

$$\bigcup_{v \in e} c(v) = [k] \quad \forall e \in E$$

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• When k = 2, same as 2-coloring of hypergraphs. NP-Hard.

Approximate Rainbow Coloring Hardness

Given a hypergraph H with m edges, it is NP-Hard to distinguish between

1. *H* is 2-colorable.

2. *H* cannot be rainbow colored with $\Omega\left(\frac{\log m}{\log \log m}\right)$ colors.

Hardness of approximate Rainbow Coloring



Label Cover

In the Label Cover problem, the input is a bipartite graph $U \cup V, E$ with projection constraints $\Pi_e : \Sigma \to \Sigma$ on each edge.

- The objective is to assign labels from Σ to the vertices to satisfy as many constraints as possible.
- Very hard to approximate: NP-Hard to find a labeling satisfying ϵ fraction of the constraints on fully satisfiable instances.
- "Mother of most optimal inapproximability results".

Approximate Rainbow Coloring Hardness

• Gadget reduction based on Label Cover-Long Code framework.

Approximate Rainbow Coloring Hardness

- Gadget reduction based on Label Cover-Long Code framework.
- Difference from the previous results: we now use very weak Label Cover hardness.
- We just use NP-Hardness of Label Cover, so alphabet size is O(1).