

Adaptive Bin Packing with Overflow

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Mohit Singh

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Georgia Tech

Bin Packing Seminar 2021

Motivation

Why should we care?

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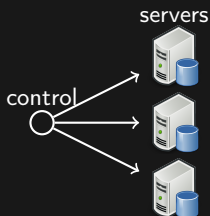
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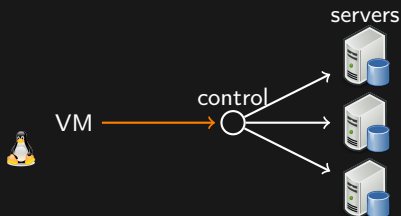
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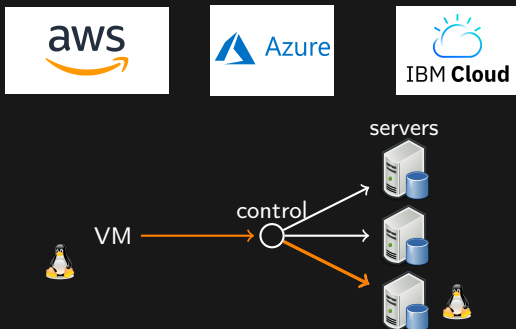
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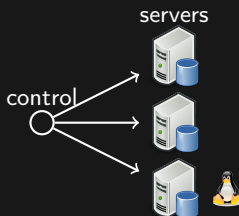
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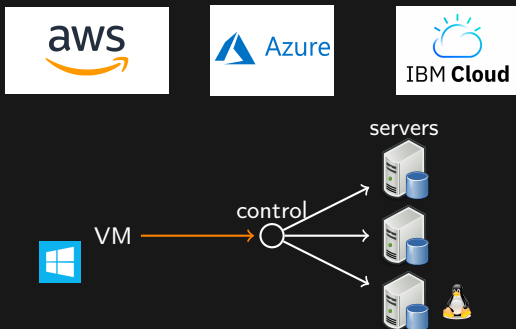
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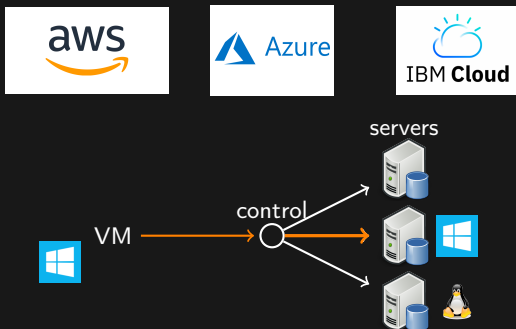
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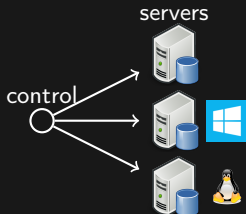
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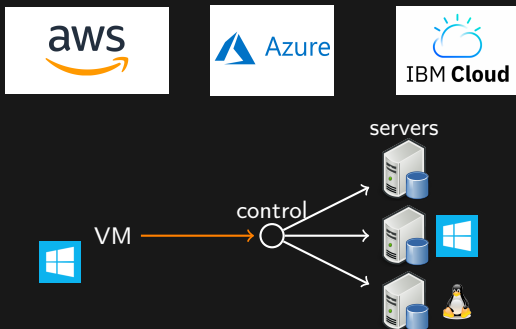
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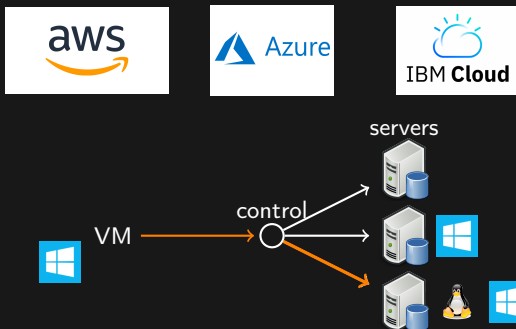
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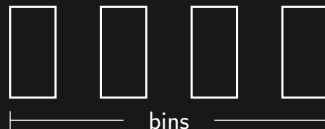
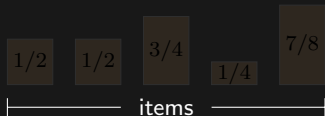


Online Bin Packing

Framework

- ▶ Assign items with sizes ≤ 1 into minimum amount of unit-capacity bins
- ▶ Examples
 - Assigning VM to servers [Gupta, Radovanovic]
 - Bandwidth allocation [Kleinberg, Rabani & Tardos]

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The stochastic viewpoint

- ▶ Uncertainty of items' sizes → probability distributions

- ▶ Stochastic bin packing [Coffman et al '80]
- ▶ Sum of squares [Csirik et al '02]

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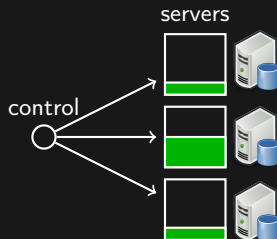
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- ▶ (Outcome) size observed **before** packing
- ▶ In many applications this is **unrealistic**

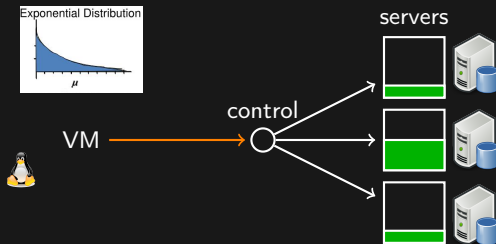
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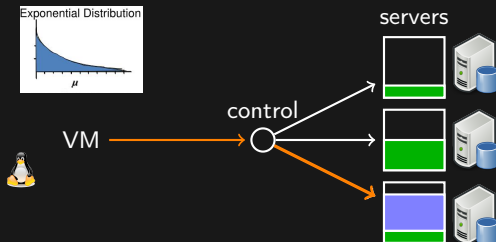
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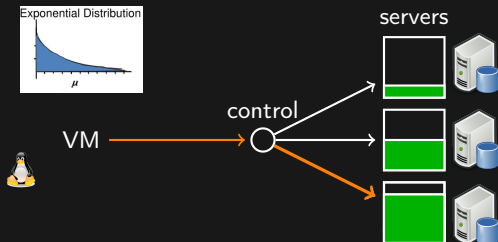
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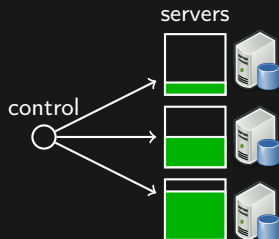
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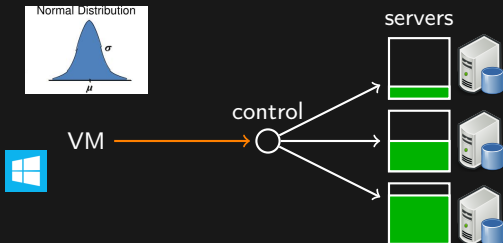
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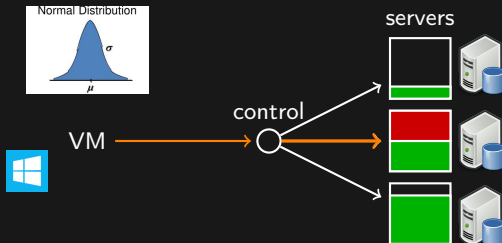
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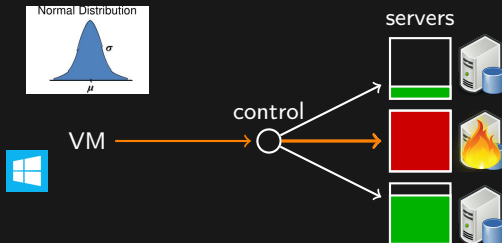
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“The global cloud computing market size is expected to grow from **USD 371.4 billion in 2020 to USD 832.1 billion by 2025** ... Digital business transformation has entered a more challenging and urgency-driven phase due to the COVID-19 pandemic.”

Research and Markets, report 5136796

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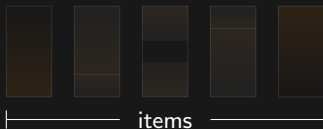
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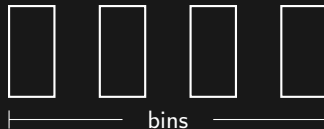
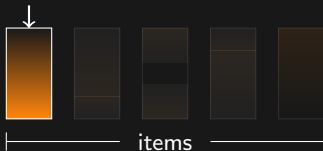
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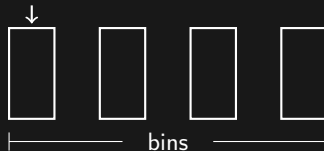
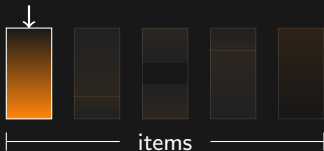
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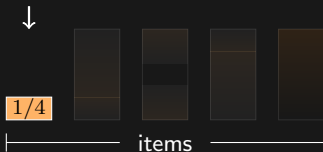
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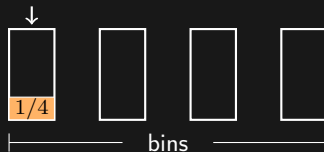
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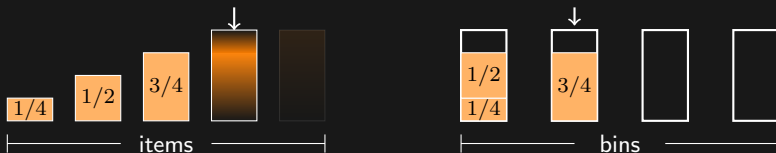
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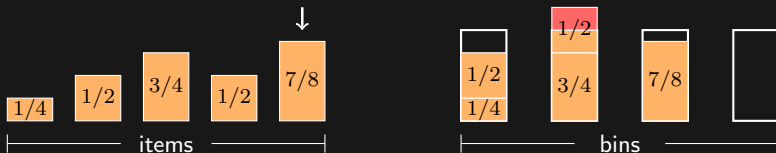
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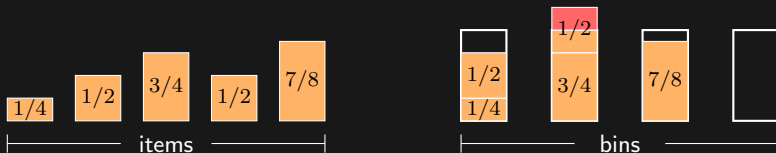
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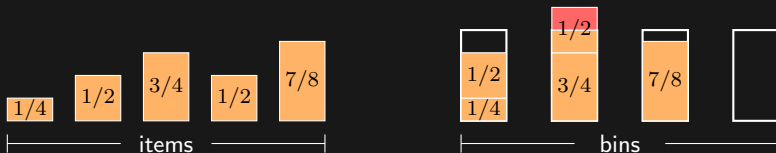
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$$\text{total cost} = 3 + C$$

Extensible models

- ▶ Generalized extensible bin packing problem [Levin '19]
- ▶ Stochastic extensible bin packing [Sagnol, Schmidt & Tesch '18]
- ▶ Online bin packing with overload cost [Luo '21]

Adaptive models

- ▶ Adaptive knapsack [Derman, Lieberman & Ross '78][Dean, Goemans & Vondrák '08]
- ▶ GAP [Alaei et al '13]
- ▶ Bipartite matching [Mehta et al '14][Goyal & Udwani '19]
- ▶ Probing submodularity [Gupta, Nagarajan & Singla][Adamczyk & Sviridenko]

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There is an algorithm ALG such that $\text{cost}(ALG) \leq (3 + 2\sqrt{2})\text{cost}(OPT)$ when X_1, \dots, X_n are i.i.d.

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Result 2 (OFFline)

For any X_1, \dots, X_n , there is a PTAS that computes a policy for bins with capacity $1 + \varepsilon$ and cost $\leq (1 + \varepsilon)\text{cost}(OPT)$.

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OPT is best sequential policy that packs X_1, \dots, X_n sequentially

Result 2 (OFFline)

For any X_1, \dots, X_n , there is a PTAS that computes a policy for bins with capacity $1 + \varepsilon$ and cost $\leq (1 + \varepsilon)\text{cost}(OPT)$.

Result 3 (OFFline)

Computing $\text{cost}(OPT)$ is $\#P$ -hard.

Some of our results

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There is an algorithm ALG such that $\text{cost}(ALG) \leq 8 \cdot \text{cost}(OPT)$ when X_1, \dots, X_n are i.i.d.

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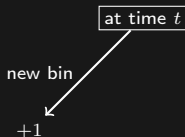
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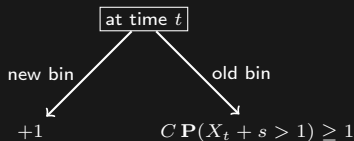


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$$\text{cost} \geq C \left(\frac{n}{2C} \right) = n/2$$

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$$\text{risk}(B_1) + \mathbf{P}(X_1 > 1) \leq \frac{1}{C}?$$

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$$\begin{aligned} \text{risk}(B_1) + \mathbf{P}(X_3 + 1 > 1) &\leq \frac{1}{C}? \\ &= \frac{2}{C} \end{aligned}$$

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bins	B_1	B_2	B_3	\dots

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Can show $\text{cost} \leq 2\frac{n}{C} + 1$

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Proposition

For bins in Budgeted Greedy, $\text{risk}(B_j) \leq \frac{1}{C}$. Therefore,

$$\begin{aligned}\text{cost}(\text{ALG}) &= \mathbf{E}[N_{\text{ALG}}] + C \cdot \mathbf{E}[O_{\text{ALG}}] \\ &= \mathbf{E}[N_{\text{ALG}}] + C \cdot \sum_j \mathbf{E}[\text{risk}(B_j)] \\ &\leq 2 \mathbf{E}[N_{\text{ALG}}].\end{aligned}$$

Where we are ...

- ▶ $\text{cost}(\mathcal{P}) = \mathbf{E}[N_{\mathcal{P}}] + C \cdot \mathbf{E}[O_{\mathcal{P}}]$
- ▶ Phase 1: ✓
 - Notion of **risk** of bin $\rightarrow \mathbf{E}[O_{\mathcal{P}}] = \text{sum of risks of bins}$
 - $\text{cost}(\text{ALG}) \leq 2 \mathbf{E}[N_{\text{ALG}}]$
- ▶ Phase 2:
 - Only bounded-risk policies are interesting: $\text{cost}(\mathcal{P}_{\text{new}}) \leq 4 \cdot \text{cost}(\mathcal{P}_{\text{old}})$
- ▶ Phase 3:
 - $\mathbf{E}[N_{\text{ALG}}] = \min_{\substack{\mathcal{P} \\ \text{bounded} \\ \text{risk}}} \mathbf{E}[N_{\mathcal{P}}]$

Only bounded risk policies are interesting

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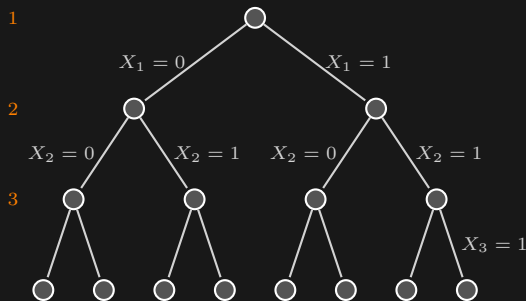
Theorem

For any policy \mathcal{P} for packing X_1, \dots, X_n , there is a policy \mathcal{P}' with risk $\leq 1/C$ such that $\text{cost}(\mathcal{P}') \leq 4 \text{cost}(\mathcal{P})$.

Only bounded risk policies are interesting

Theorem

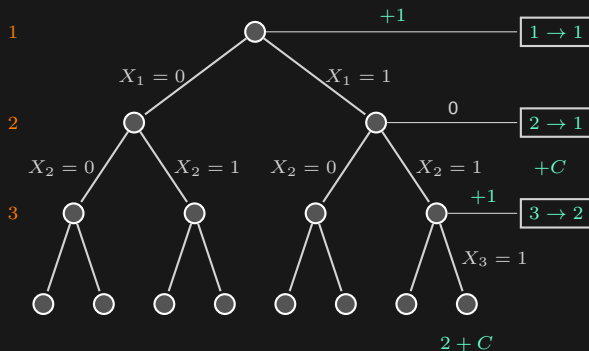
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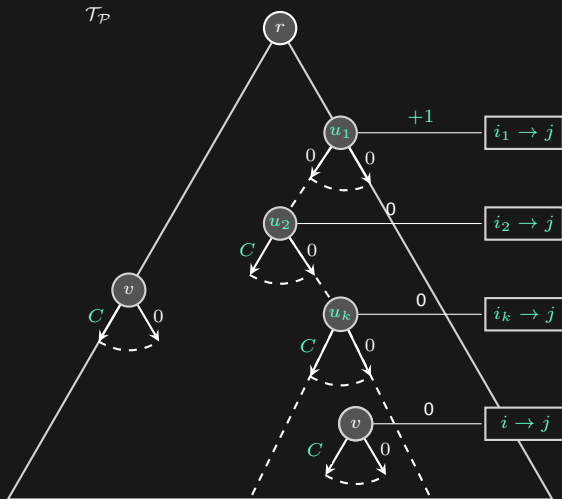
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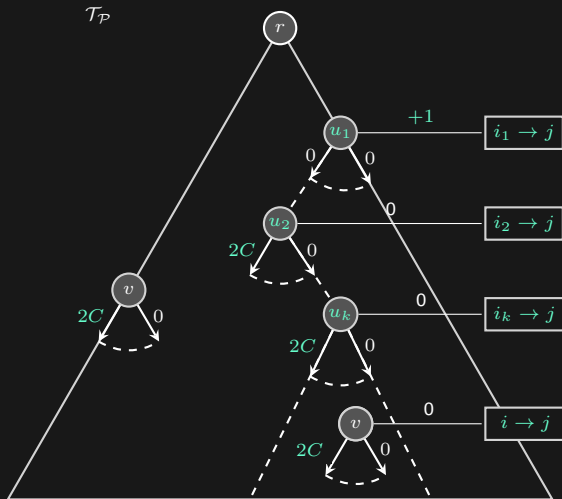
$X_1, X_2, X_3 \sim \text{Bern}(1/C)$

Proof



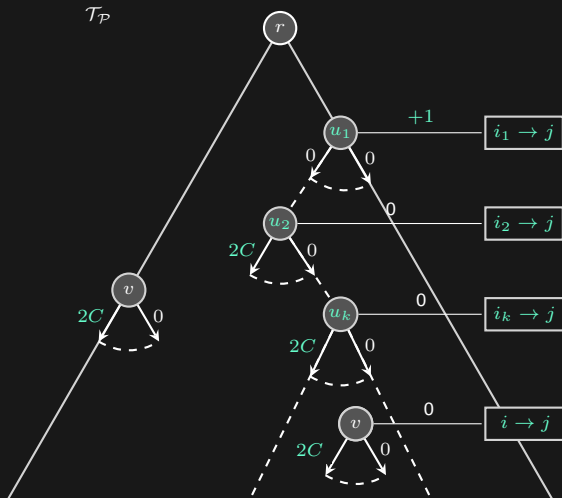
$\text{cost}(\mathcal{P})$

Proof



$$\text{cost}'(\mathcal{P}) \leq 2 \text{cost}(\mathcal{P})$$

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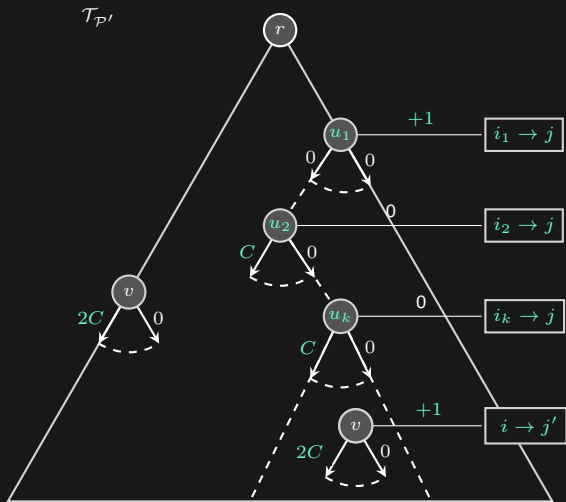
$$\text{risk}_j = \mathbf{P}(X_{i_1} > 1) \leq \frac{1}{C}$$

$$\text{risk}_j \leq \frac{1}{C}$$

$$\text{risk}_j > \frac{1}{C}$$

$$\mathbf{P}(X_{i_1} \text{ overflows } j) + \mathbf{P}(X_{i_2} \text{ overflows } j) + \dots$$

Proof



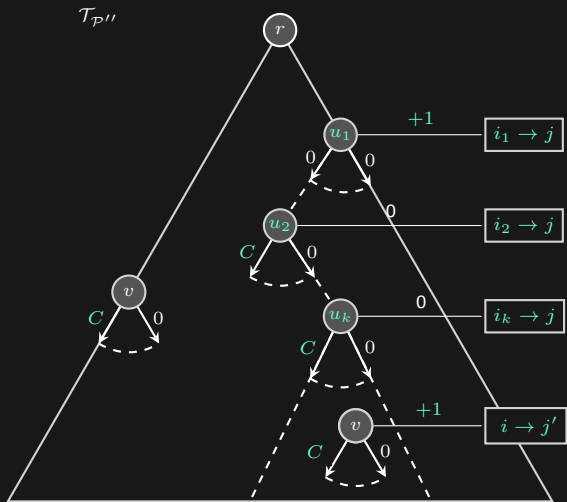
$$\text{cost}''(\mathcal{P}') \leq 2 \text{cost}(\mathcal{P})$$

$$\text{risk}_j = \mathbf{P}(X_{i_1} > 1) \leq \frac{1}{C}$$

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$$\text{risk}_j > \frac{1}{C}$$

Proof



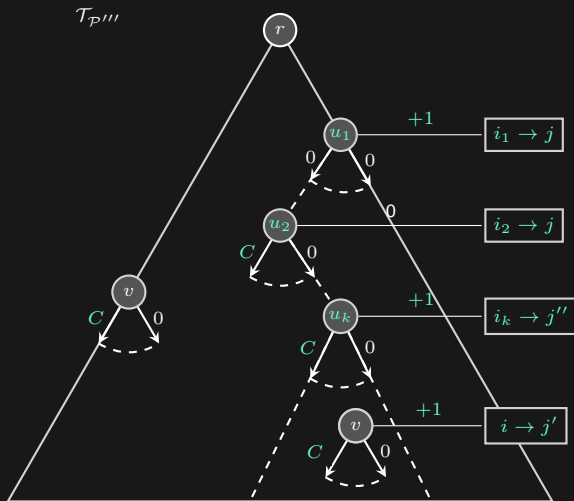
$$\text{cost}(\mathcal{P}'') \leq 2 \text{cost}(\mathcal{P})$$

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$$\text{cost}(\mathcal{P}''') \leq 4 \text{cost}(\mathcal{P})$$

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Where we are ...

- ▶ $\text{cost}(\mathcal{P}) = \mathbf{E}[N_{\mathcal{P}}] + C \cdot \mathbf{E}[O_{\mathcal{P}}]$
- ▶ Phase 1: ✓
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 - $\text{cost}(\text{ALG}) \leq 2 \mathbf{E}[N_{\text{ALG}}]$
- ▶ Phase 2: ✓
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 - $\mathbf{E}[N_{\text{ALG}}] = \min_{\substack{\mathcal{P} \\ \text{bounded} \\ \text{risk}}} \mathbf{E}[N_{\mathcal{P}}]$

Number of Bins of Budgeted Greedy

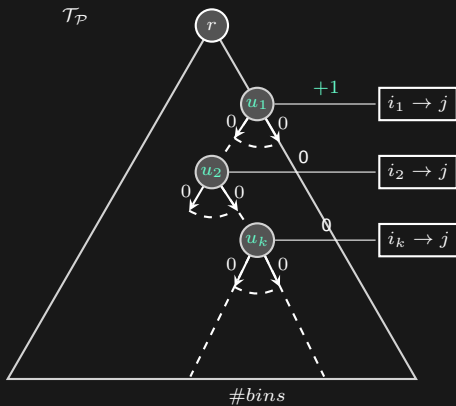
Theorem

$\mathbf{E}[N_{\text{ALG}}] = \min_{\mathcal{P} \text{ bounded risk}} \mathbf{E}[N_{\mathcal{P}}]$ if X_1, \dots, X_n are i.i.d.

Number of Bins of Budgeted Greedy

Theorem

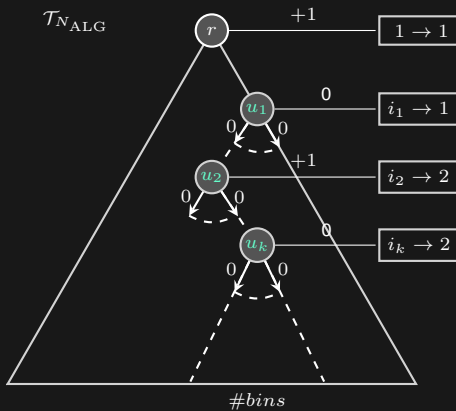
$\mathbf{E}[N_{\text{ALG}}] = \min_{\mathcal{P}} \text{bounded risk } \mathbf{E}[N_{\mathcal{P}}]$ if X_1, \dots, X_n are i.i.d.



Number of Bins of Budgeted Greedy

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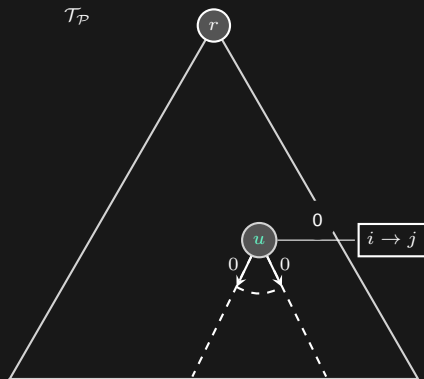


- i to bin j pack if $\text{risk}(B_j) + \mathbf{P}(X_i \text{ overflow } j) \leq 1/C$
- $\text{risk}(B_j) \leftarrow \text{risk}(B_j) + \mathbf{P}(X_i \text{ overflow } j)$

Number of Bins of Budgeted Greedy

Theorem

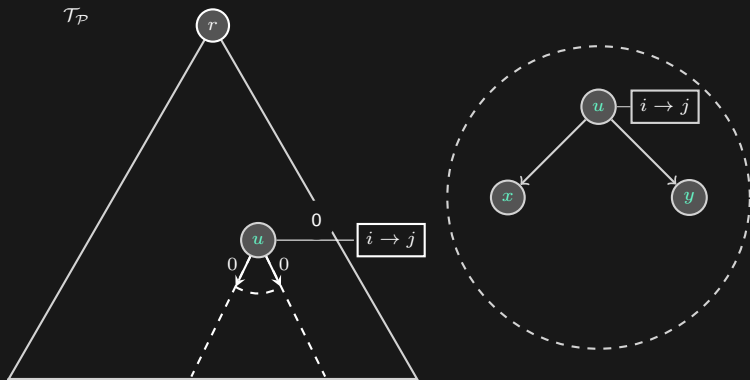
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Number of Bins of Budgeted Greedy

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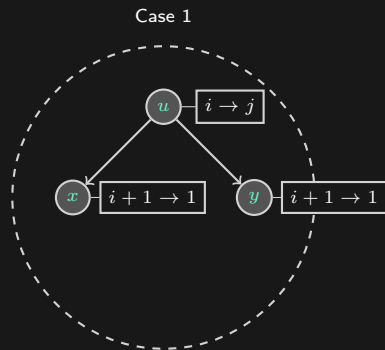
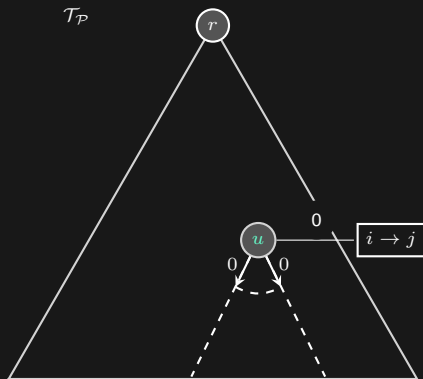
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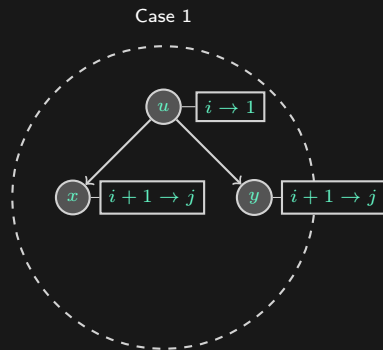
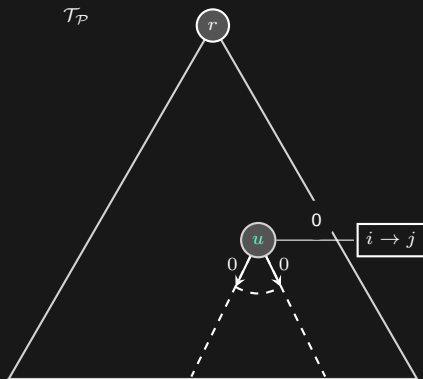
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Theorem

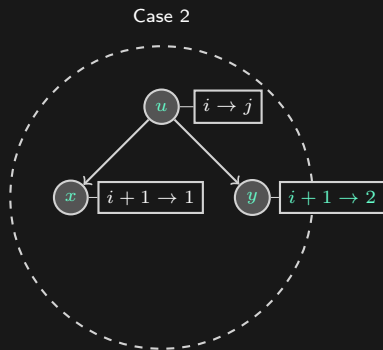
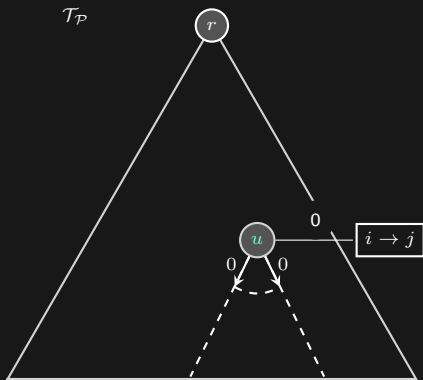
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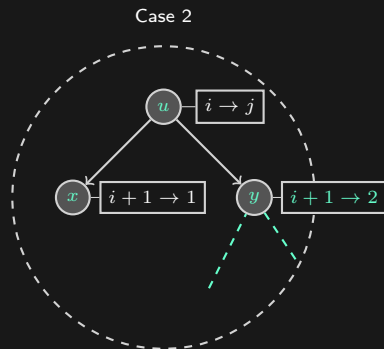
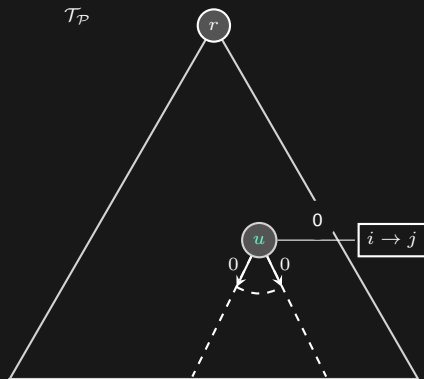
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Number of Bins of Budgeted Greedy

Theorem

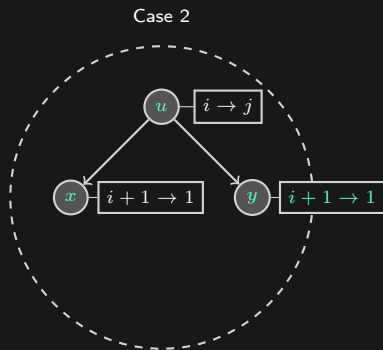
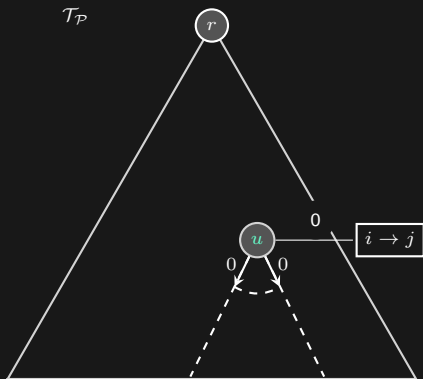
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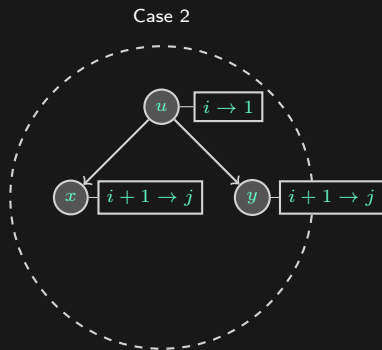
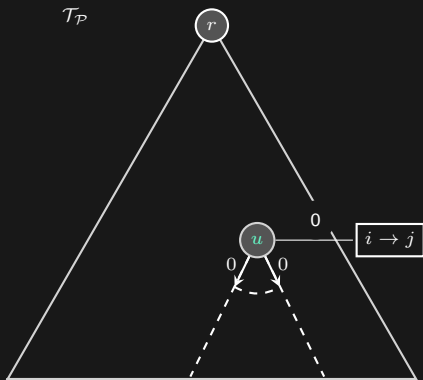
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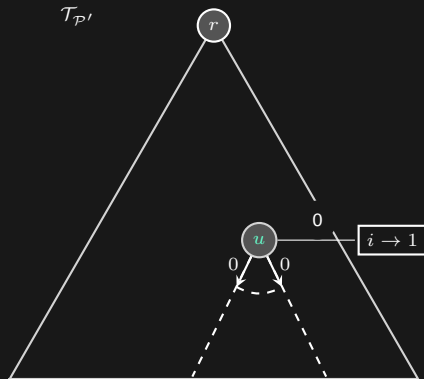
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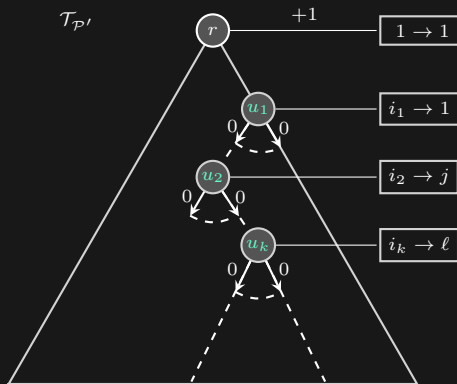
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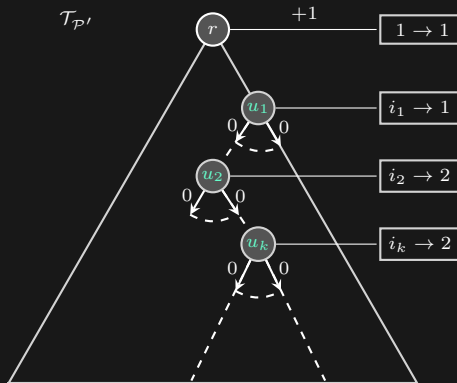
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Then ...

- ▶ $\text{cost}(\mathcal{P}) = \mathbf{E}[N_{\mathcal{P}}] + C \cdot \mathbf{E}[O_{\mathcal{P}}]$
- ▶ Phase 1: ✓
 - Notion of **risk** of bin $\rightarrow \mathbf{E}[O_{\mathcal{P}}] = \text{sum of risks of bins}$
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$$\text{cost}(\text{ALG}) \leq 2 \mathbf{E}[N_{\text{ALG}}] \leq 2 \mathbf{E}[N_{\mathcal{P}_{\text{new}}}] \leq 2 \text{cost}(\mathcal{P}_{\text{new}}) \leq 8 \text{cost}(\mathcal{P}_{\text{old}})$$



Some comments

- ▶ Careful analysis gives us the factor $3 + 2\sqrt{2} \approx 5.828$
- ▶ Budgeted Greedy also exhibits $\mathcal{O}(\log C)$ factor against *arbitrary* exponential distributions
- ▶ There are non-identical distributions in which Budgeted Greedy fails:
 - $\text{cost}(\text{ALG}) = n/2$ but $\text{cost}(\text{OPT}) \leq n/C$
- ▶ Still open for arbitrary distributions

Summary

- ▶ New packing model for items with random sizes
 - Outcomes are observed right after packing item
 - Overflowing bins incur in penalty

Model	Positive results(?)	Hardness(?)
Online	$3 + 2\sqrt{2}$ factor for i.i.d. input $\mathcal{O}(\log C)$ factor for exponential $\mathcal{O}(1)$ factor for exponential distributions if rates are larger than $2\log C$	$\Omega(\sqrt{\log C})$ factor for exp.
Offline	PTAS with extra capacity	#P-hard

- ▶ Preprint: <https://arxiv.org/abs/2007.11532v2>
- ▶ My site: <https://sites.google.com/view/sebastianps>