

Gossip beyond broadcasting: gossip based aggregation

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The gossip based communication model

- An example protocol: average calculation
- Components: characterization and combination
- Future work





Outline

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Nodes

BISON

- have state
- perform computations
- Communication Topology
 - Neighbors ("knows about" relation)
 - Maintained by specific protocols







Push-Pull Gossip based Communication Model

// active thread
do forever
wait(T time units)
peer = selectRandomNeighbor()
send state to peer
receive peer.state from peer
state = updateState(state,peer.state)

```
// passive thread
do forever
  (peer,peer.state) = waitMessage()
  send state to peer
  state = updateState(state,peer.state)
```





Gossip as Communication Model

- Gossip is a communication model, like eg the client-server model (as opposed to protocol)
- Its main properties are
 - proactive
 - democratic
 - potentially (depends on application)
 - scalable
 - robust
 - reliable





Gossip as Cellular Automaton

Similarities:

- Cycles (each T time units interval)
- State updates based on neighborhood state
 Differences:
 - Only one neighbor is used in a cycle
 - Not `generational' but `steady state'
 - Topology can be arbitrary
 - Topology can dynamically change over time





Expressivity

- It supports lots of very different protocols and design philosophies, not only information dissemination
 - epidemics
 - infomation dissemination, aggregation (max)
 - diffusion
 - aggregation (avg), load balancing
 - topology management
 - synchronization



etc.



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The Protocol

- We apply diffusion for calculating the average
- state: current approximation of average in the whole system

updateState(s1, s2):= (s1+s2)/2

- Diffusion has lots of other applications (we will discuss them later) including
 - network size estimation

Ioad balancing

- calculating variance (or any moments)
- ×.















BISON

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Applications

The averaging protocol can compute any means in the form

$$m = f^{-1} \left(\frac{f(a_1) + \ldots + f(a_n)}{n} \right)$$

These include the following means

average	f(x) = x
quadratic	$f(x) = x^2$
harmonic	$f(x) = \frac{1}{x}$
geometric	$f(x) = \ln x$





Applications

- The averaging protocol can compute any aggregate that can be expressed by a function of some means. For instance
 - variance: using avg. and avg. of squares
 - network size: 1/average if only one node holds 1 the rest 0
 - sum: network size times average
 - any n-th moment: using n-th power averages
 - coefficients of mathematical models like linear regression
 - statistical tests
- etc...



Some Observations and Questions

- The procedure is convergent if the graph is connected
- Each node converges to the average of the original values
- How fast is convergence on different topologies?
- Which topology is optimal?
- What are the key features of a topology that determine the speed of convergence?



What are the effects of node/link failure?

BISON

Some Answers

- On the fully connected topology convergence speed is exponential.
- On a random topology it is practically exponential.
- Node failure is not critical.
- Link failure is not critical.





Framework

A local protocol

do	forever
	<pre>wait(getWaitingTime())</pre>
	nj = selectRandomNeighbor()
	<pre>// perform elementary aggregation step</pre>
	send a[i] to nj
	receive a[j] from nj
	a[i] = (a[i] + a[j])/2





The base theorem

- Each pair of values selected by the index pairs returned by each call to getPair are uncorrelated,
- the random variables $\varphi_1, \ldots, \varphi_N$ are identically distributed. Let φ denote a random variable with this common distribution,
- After (i, j) is returned by getPair the number of times i and j will be selected by the remaining calls to getPair has identical distribution.

THEN:

IF:

$$E(\boldsymbol{\sigma}_{i+1}^2) \approx E(2^{-\varphi})E(\boldsymbol{\sigma}_i^2)$$





Convergence factor

 getPair defined by the local protocol when each node contacts a peer regularly
 A local corresponding protocol exists

$$P(\varphi = j) = \frac{1}{(j-1)!} e^{-1} \to E(2^{-\varphi}) = \frac{1}{2\sqrt{e}}$$









Link Failure

Any given link fails with probability P_d
 The effect of this is only slowdown. In particular the rate can be bounded as follows

f
$$E(\boldsymbol{\sigma}_{i+1}^2) = \rho E(\boldsymbol{\sigma}_i^2)$$
 then

$$\rho_d \leq \left(\frac{1}{e}\right)^{1-P_d} = e^{P_d - 1}$$





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Topology (lpbcast, newscast)

- State: neighbor list: constant sized list of peer adddresses
- updateState(s1,s2): select new list randomly or based on some additional information
- selectRandomNeighbor() can be biased based on (partial) information on the state of the peers
- based on particular implementation details, generates different topologies





Broadcasting

- State: `infected' or not, ie received information or not
- updateState(s1,s2): if received state is infected, set state to infected
- pull brodcast is also possible: efficient, not adaptive
- selectRandomNeighbor() can be biased based on (partial) information on the state of the peers



not flooding, even with random neighbor selection



Aggregation

- State: current approximation of aggregate
 - updateState(s1, s2): elementary aggregation step, examples include
 - (s1+s2)/2 for average
 - (s1s2)^{1/2} for geometric mean
 - max(s1,s2) for maximum
 - min(s1,s2) for minimum
- combining elementary aggregations more complex functions can be computed such as sum, set size, variance, etc.





Synchronization

- State: current epoch. The synchronization point is the beginning of each epoch.
- An epoch has a fixed time length, and incremented based on a local clock
- updateState(s1,s2): the maximal epoch
 identifier: max(s1,s2)
- solves problems of clock drift, joinings, failures, message delays
- General building block to be used by all applications needing synchronization





Characterization of Components

A component or building block is a protocol defining a self organizing system that provides a function through a standard interface. (Eg average calculation.)

- topology or function
- fast or slow
 - self organizing systems need time to converge or adapt; this process can be fast ot slow
 - slow protocols may rely on fast ones
- adaptive or convergent (static)
 - a self organizing system can converge to a stable state or it can react to the environment





Combination of Components

- The goal is reusability to facilitate research (simpler problems) and development (off-the-shelf components)
- Some rules of thumb for combination
 - slow functions can utilize fast functions on the fly (topology, aggregation)
 - expensive functions can utilize cheap functions for optimization
- At the root there is always a topology (membership) protocol









- Fast average calculation provides optimal load (fast, not optimal, cheap)
- Slow load balancing optimized based on the knowledge of optimal load (slow, optimal, expensive)



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Future Work

- New functions
- More formal framework for composition
- Security
 - security of components: mutual auditing
 - security component?
- Simulation
 - realism vs. scalability: the study of the simplifying assumptions of peersim
- Visulization
- AHN, sensor networks?





- Gossip comunication model is a general paradigm
- Gossip based aggregation is shown to be
 - scalable (results independent of N)
 - fast
 - robust
- Possibility to combine functions

information processing/control

- topology management
- ×.